

3D Ionospheric Tomography using Finite Elements







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Agenda

- Goals of ionospheric imaging
- Tomography on 2D model
 - Interpolation artefacts
 - Self-consistent tomography

• 3D finite-element tomography

- Tetrahedral grids
- Pure GPS least-squares fits
- Mixed IRI+GPS assimilative model

• Outlook





Ionospheric imaging



- 3D ionospheric density profiles would be extremely powerful in understanding ionospheric effects
 - e.g. RF ray-tracing, HF reflection heights, GPS time-offsets, etc.
- Direct measurement of 3D electron densities is not practicable
 - Assessing estimated densities against "truth" is also challenging
- Density profile must be inferred by some form of model-fitting process from sparse measurements
 - Dual-band GPS, ionosonde traces, etc.
- Many tomographic models have been developed using various approaches
 - e.g. empirical orthonormal functions, 2D vertical slices, 2½D shells, iterative or exact leastsquares, assimilative Kalman filters, etc.
- Optimal use of limited sensor data requires careful control of artefacts created by the fitting process

Idealized 2D assimilation of GPS TEC







2 clouds, 100 rays, 9x9 grid

Two distinct interpolation phases



- Each observation needs to be linked to the grid-cells through which it passes
- The node-weights need to be adjusted to best-fit the measurements
 - This requires interpolating between nodes to compare with the measurements



- A rendered image can be constructed from the fitted corner weights
- This may have many more pixels than there are nodes in the grid
- This typically involves regular interpolation within grid cells

Tomographic fit (naïve interpolator)





- Piecewise-constant nearest-neighbour interpolator produces very crude image
 - Strong discontinuities
 - Ambiguities over shape & number of clouds
 - Strong blurring
 - Spurious cloud-like features

Tomographic fit (naïve post-processing)



- Tomographic fit, and final image, can use different interpolation schemes
 - Here, piecewise-constant for fitting, bi-linear for rendering
- Still poor resolution of cloud features, blurring, misplacement of cloud centre, etc.

Tomographic fit (non self-consistent)





- Using mismatched fitting/rendering interpolators gives choice of different artefacts
 - Here, corner-average for fitting, bi-linear for rendering

• Still poor resolution of cloud features, blurring, etc.

Cloud centre happens to be more accurate

Tomographic fit (smoothly self-consistent)





- Using the same interpolation function in fitting & rendering produces the highest quality images
 - Requires more complex algebra, but computational cost is almost identical
 - Makes optimal use of limited sensor data

Tetrahedral grids for 3D tomography



- Optimal tomographic fitting requires being able predict how each interpolation weight would affect any GPS TEC measurement
 - This requires being able to efficiently integrate each basis-function along a ray between satellite and receiver
- Choosing suitable 3D basis-functions (or grids) is challenging
 - Undesirable choices include: piece-wise constant; latitude/longitude/altitude grids; etc.
- Tetrahedral grids with piecewise-planar interpolation have attractive theoretical properties:
 - Efficient calculation of line-integrals for GPS TEC assimilation
 - Naturally avoid unphysical discontinuities in electron density
 - Allow multi-resolution grids, e.g. to give finer coverage of operational regions
 - Require no special handling of polar regions (unlike rectangular latitude/longitude grids)

Tetrahedral grid manipulation

- 3D tetrahedral grids need to avoid gaps or overlaps between adjacent tetrahedra
- Grids can be generated by subdividing cuboids
 - Not ideal for conforming to Earth's curvature
- More flexible approach is to fit tetrahedra to a set of sample points
 - Generate sheets of sample points at fixed altitudes
 - Use Delaunay triangularization to find optimal set of tetrahedra filling the convex hull
- Specialized indexing is necessary to allow efficient density queries





Example global & local tetrahedral grids



Bottom-side visibility using GPS TEC



- GPS tomography relies on having multiple look-directions through any point of interest
- At low altitudes, only a single GPS receiver may have visibility due to curvature of the Earth
- Simulated scenario has been generated using IRI-2016 and realistic GPS orbits
 - Provides access to complete information about "correct" tomographic fit
 - Provides clean GPS time-series without need to estimate biases



Tomographic fits to synthetic IRI dataset

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"True" TEC from IRI-2016

TEC from tomographic fit to synthetic GPS data

Finite-element assimilation via Bayesian inference



- Historical data provides valuable guide to 3D electron-density profile
 - Especially useful to "fill-in" gaps in GPS coverage
 - Useful as soft constraint on typical shape of density profiles
- Assimilative model of ionospheric electron density can use IRI as a background (statistical prior)
- Finite-element model can be used as multiplicative correction to background $\rho(r,t)=\rho_{bgnd}(r,t)\,e^{\phi(r,t)}$
- Tuning of finite-element weights can be driven by a Bayesian inference (MAP) process

$$\rho(r,t) = \sum_{\mu} a_{\mu} B_{\mu}(r,t)$$

- Weights sensor data and background trends according to level of confidence
- "EDAM2" model assimilates GPS TEC into IRI-2016 background
 - Tetrahedral grid techniques very similar to pure GPS tomography

Automatic estimation of GPS biases



- Inter-frequency time-delays need to be calibrated before real GPS TEC values can be used for tomography
 - Using phase-rate avoids this, but makes for a more complicated tomographic model
- GPS bias parameters can be incorporated into tomographic or assimilative model
- Suppression of negative TEC values is a basic sanity check of the tomographic fit

Recovery of foF2 trends





• Test scenario assimilates 19 GPS stations across Europe, compared against 'DB049' ionosonde in Belgium

- DB049 is not used in the assimilation
- Vertical profiles above DB049 provide direct comparison between "truth" and assimilative model
 - Altitude (hmF2) and level (foF2) of maximum density provide convenient measure of success



Fidelity of hmF2

- Time-series of foF2 shows that estimation of bottom-side features can be improved using GPS
- Correlation of hmF2 with "truth" from ionosonde has been computed for entirety of August 2016
- EDAM2 model shows closer match of true variance than IRI or earlier EDAM model



Summary



- Estimating 3D electron-density profiles is challenging given the sparsity of GPS and ionosonde data
- Rigorous treatment of interpolation is important to best use of sparse sensor data in tomographic fitting
 - Popular piecewise-constant interpolation introduces artefacts and/or increases computational cost
- Finite-element techniques provide an effective means of performing 3D tomography
- Pure tomographic fits to GPS data are able to recover large-scale ionospheric features
 - Indicative of physical limits, independent of historical data or empirical profiles
- Finite-element techniques can be used effectively in combination with background models (e.g. IRI) to allow statistical inference of 3D electron –density profile



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